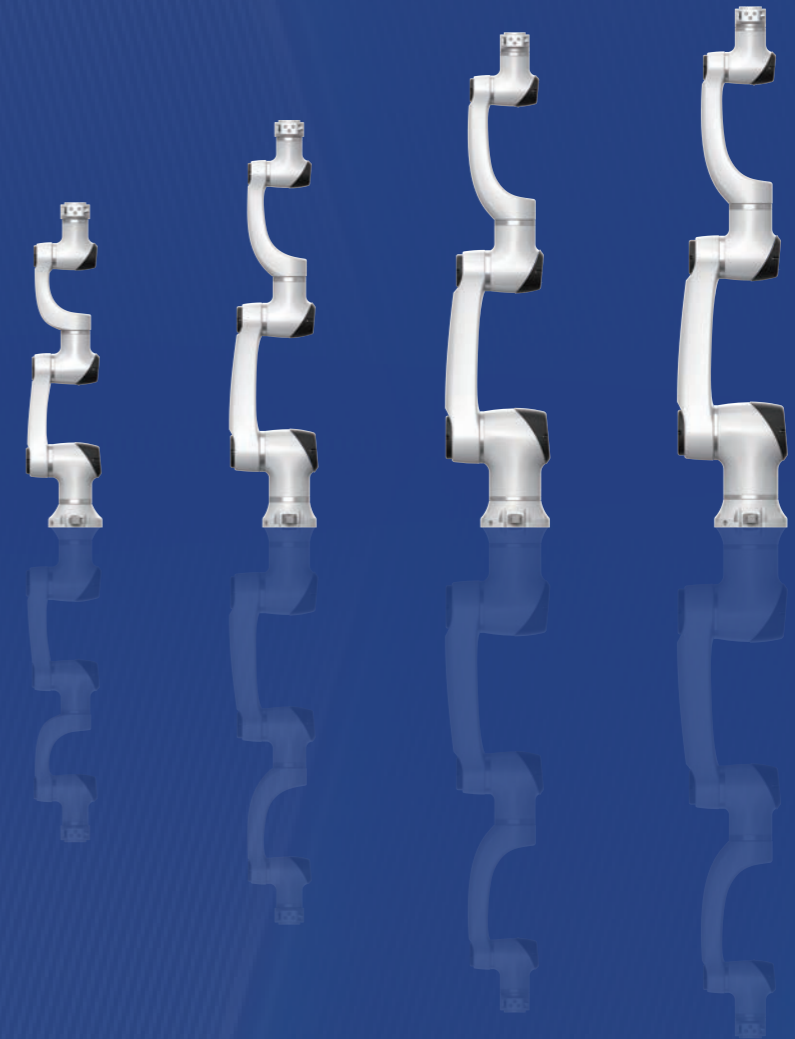


UK & Ireland Official Distributor



International service hotline

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Shenzhen Han's Robot Co., Ltd.

www.hansrobot.net

Catalogue

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Company Profile



Vision

To be the global leader
in the era of intelligent
robots

Mission

Serve humanity with
robot technology

Values

Lead, fast-speed, service,
sharing, passion,
enthusiasm, curiosity

Shenzhen Han's Robot Co., Ltd., invested and established by Han's Laser Technology Group (stock name: Han's Laser, stock code: 002008), is a high-tech enterprise established on the basis of the Robot Division from Han's Motor. It was founded in August, 2017 with its headquarter and production base located in Han's Laser global intelligent manufacturing base, Bao'an District, Shenzhen. Han's Robot is dedicated to the development, promotion and application of intelligent robots in industry, healthcare, logistics, services and so on, becoming the global leader in the era of intelligent robots.

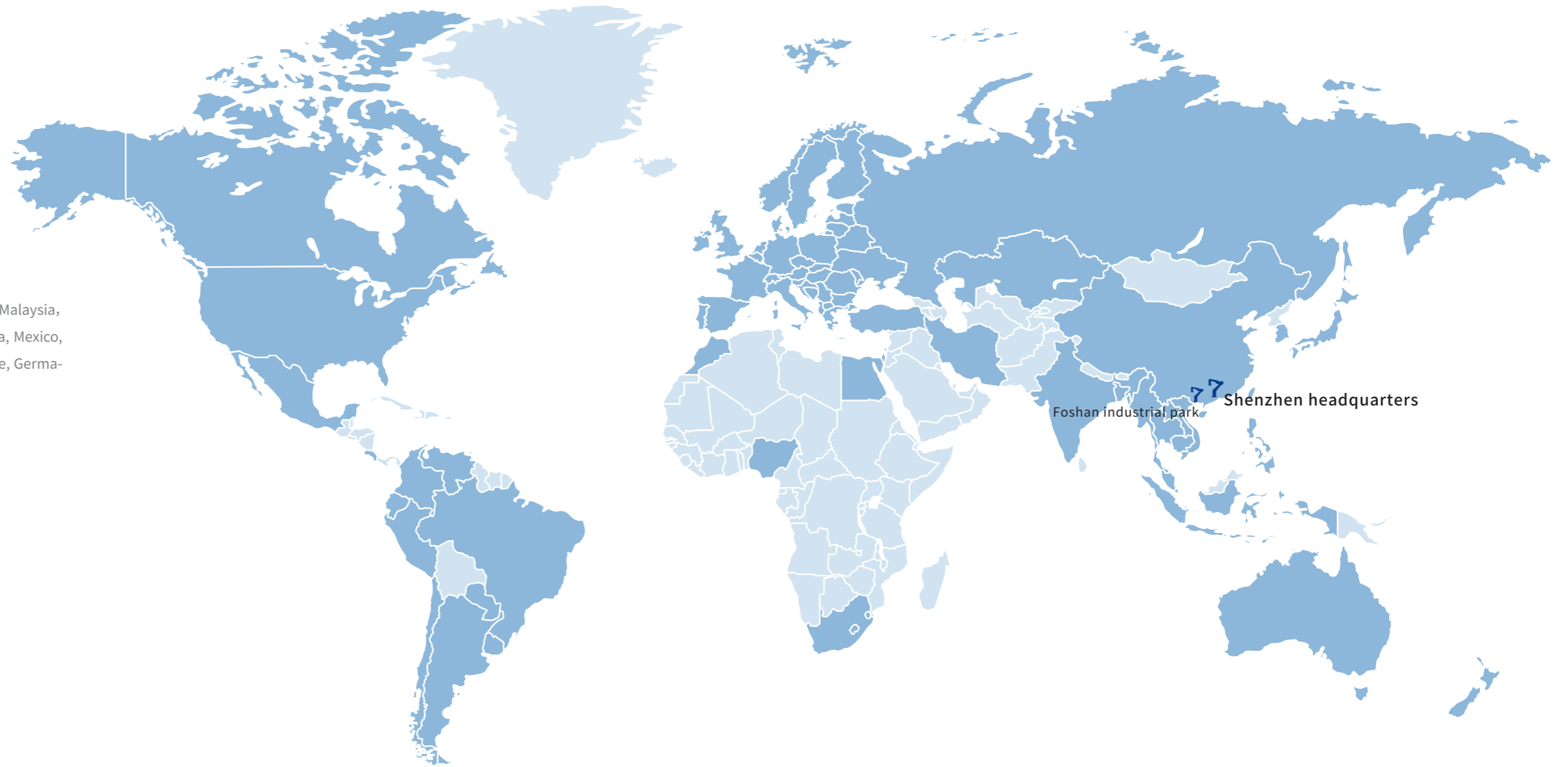
Global Service Network

Partners from more than 100 countries

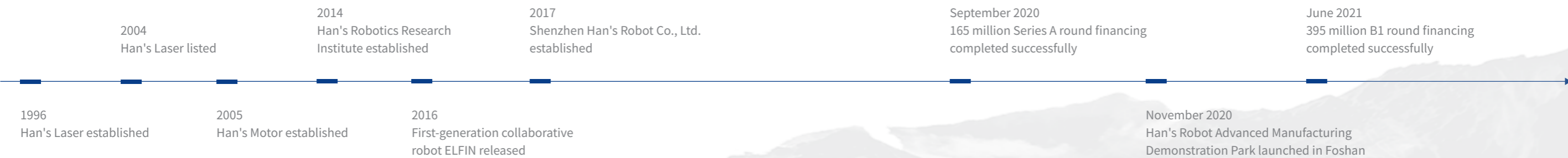
China, South Korea, Japan, Thailand, Singapore, Malaysia, Australia, New Zealand, the United States, Canada, Mexico, Brazil, Colombia, Argentina, Russia, Britain, France, Germany, Spain, the Netherlands, Italy, etc.

Top talents from 25+ countries & regions

400+ Employees
200+ Professional engineers
25+ Countries



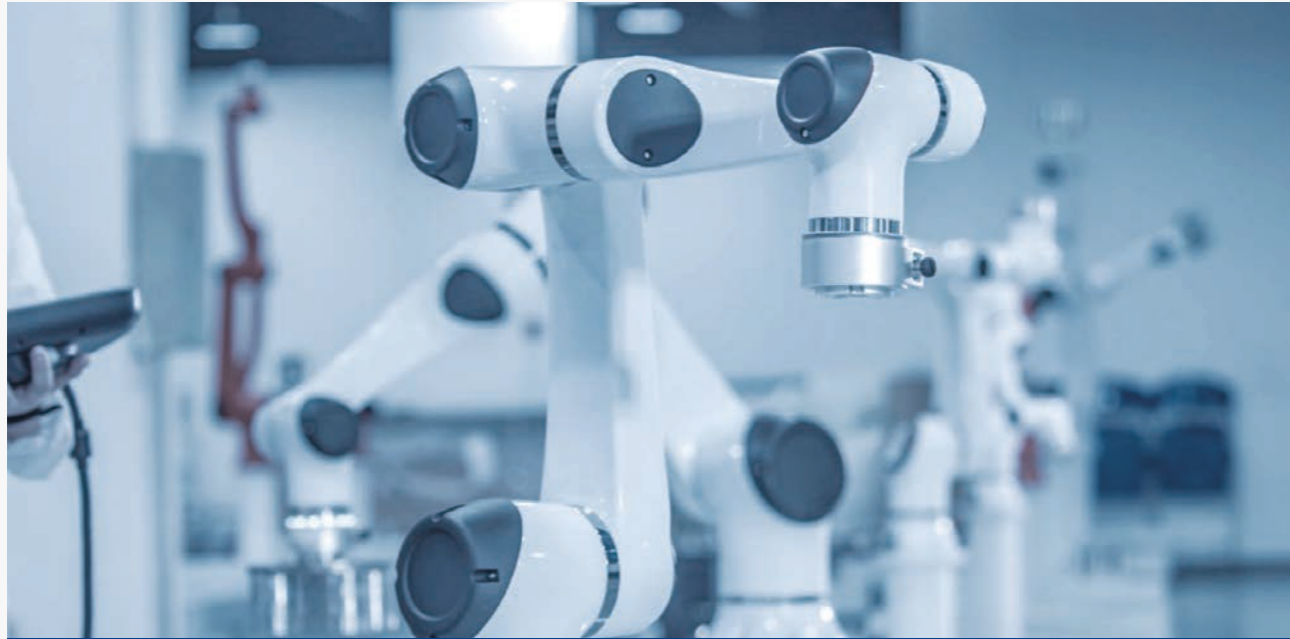
Milestones





Han's Robot

Product Advantages



Han's Robot has been constantly exploring the breadth and depth for serving human by its self-developed leading collaborative robot technologies. The payload of the robots vary from 3kg to 18kg which can meet the requirements of various customers. Moreover, Han's Robot has developed products from the first generation 6-axis collaborative robots Elfin robot to the second-generation Elfin-P robot with higher performance.



Each joint with a motion range of $\pm 360^\circ$

- High motion efficiency ✓
- More possible positions of high difficulty ✓
- Most flexible collaborative robot ✓
- Low power consumption ✓



Self-developed dual-joint modules

- Self-developed dual-joint modules ✓
- Unique arm design, optimized singularity points ✓
- Higher integration ✓
- Higher flexibility ✓

EtherCAT
EtherCAT bus communication

- Strong anti-interference ability ✓
- High communication frequency and fast speed ✓
- High safety, accurate motion trajectory ✓
- Accessible data for all joints ✓



Self-developed of core components

- Completely self-developed core components from Han's Group ✓
- Complete set of motors, servo drive ✓
- Grating encoder, 6-dimensional force/torque sensor ✓
- Electromagnetic brake, high-speed inverter ✓

Advantages



Innovative brake method

- The robot will automatically rebound and then stop when encounter any resistance. ✓
- Output force and power controlled within the safety range to ensure personnel safety. ✓
- Innovative brake design. The robot will be locked immediately in case of a sudden power failure or emergency stop during operation. It will not slide, fall or move at all ✓



IP66 protection rating

- Higher waterproof and dust-proof protection ✓
- Suitable for harsher environments ✓
- And can avoid external objects and dust ✓
- Applicable to more working conditions ✓



ISO class 5 cleanroom

- The surface cleanliness of the whole robot is excellent due to the excellent waterproof and dust-proof performance ✓
- Optimized structure of internal parts, low mutual friction, avoiding damage ✓
- Excellent sealing of the whole robot, without impurities intrusion ✓
- Automotive and aerospace industry standards, ensuring high quality ✓



More than 16 years of industrial experience

- Incubated from the Robotics Research Institute team of Han's Motor ✓
- More than 16 years experience in motors, servo drives and motion control ✓
- Long-term cooperation with famous universities at home and abroad ✓
- Dedicated to collaborative robot technologies and applications ✓



More open platform

- Open source ROS interface, which allows users to control the robot joints in real time through EtherCAT under the ROS environment ✓
- ROS platform, which greatly improves the robot's scalability. The robot can be controlled without an additional control box ✓
- Used for ROS teaching in colleges and universities ✓



Graphical control

- Graphical software design, intuitive, easy to understand, easy to operate ✓
- User-friendly interface logic design, easy to use ✓
- The software controls the robot with instant reactions, without delay, out of control and other symptoms ✓
- Remote control via touchscreen, excellent human-machine experience ✓

Han's Robot Plug & Play Tools



Adhering to the ecological concept of "all are friends in the world", Han's Robot has created a more complete and open collaborative ecosystem, and designed various IO and communication interfaces. These IO interfaces greatly expand the application scope of the robot and can support "plug and play" with most accessories in the industrial ecosystem, such as grippers, vision, and sensors, which can meet the needs of multiple scenarios such as loading and unloading, assembly, testing, handling, screw driving, grinding, spraying etc.

Grippers

| | | | | | |
|--|-------------|--|--------|--|--------------|
| | Robotiq | | SMC | | RobustMotion |
| | Onrobot | | Schunk | | HIWIN |
| | DH-Robotics | | SRT | | |

Force Sensor

| | | | | | |
|--|------------|--|---------|--|----------|
| | Link-touch | | SRI | | Onrobot |
| | ATI | | Robotiq | | Hypersen |

Vision

| | | | | | |
|--|------------|--|-----------|--|--------------|
| | Micromatch | | Basler | | Cosmosvision |
| | Mech-Mind | | Cognex | | Seizet |
| | Keyence | | Hikvision | | UBSense |

Scan code to join us

Han's Robot Partner Ecosystem
To build an open, shared and win-win industrial ecosystem!



"POSS" Concept

The smartest body, the smartest brain:

Han's Robot believes that the characteristics of a good collaborative robot can be summarized as POSS. We are dedicated to the research and application expression of cutting-edge robotics technology, and the development of robots with the smartest body and the smartest brain.



Higher
Performance



More
Open



More
Smart



More
Safe

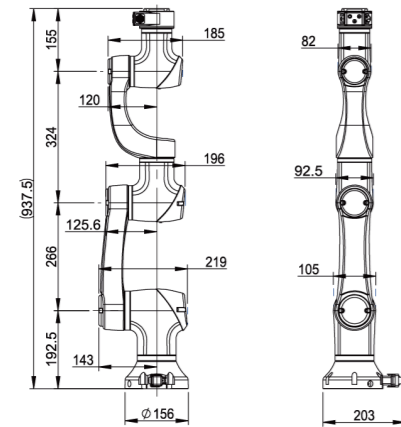
Overview



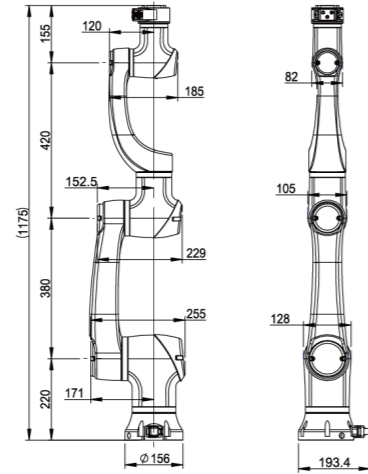
| Model | E03 | E05 | E05-L | E10 | E10-L | E15 | P03 | P05 | P05-L | P10 | P10-L | |
|-------------------------|--|------------------------------|------------------------------|--|--|---|--|------------------------------|------------------------------|--|--|--|
| Weight | 18kg | 25kg | 26kg | 43kg | 45kg | 60kg | 19kg | 26kg | 27kg | 45kg | 48kg | |
| Payload | 3kg | 5kg | 3.5kg | 10kg | 8kg | 15kg | 3kg | 5kg | 3.5kg | 10kg | 8kg | |
| Reach | 590mm | 800mm | 950mm | 1000mm | 1300mm | 1300mm | 590mm | 800mm | 950mm | 1000mm | 1300mm | |
| Power consumption | 100W typical application | 180W typical application | 180W typical application | 350W typical application | 350W typical application | 600W typical application | 100W typical application | 180W typical application | 180W typical application | 350W typical application | 350W typical application | |
| Joint range | ±360° | | | | | | ±360° | | | | | |
| Joint speed | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s | J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s | J1-J2 80°/s J3-J4 120°/s J5-J6 150°/s | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J2 120°/s J3-J4 135°/s J5-J6 180°/s | J1-J2 100°/s J3-J4 135°/s J5-J6 180°/s | |
| Tool speed | | | | 2m/s | | | | | | 2m/s | | |
| Repeatability | ±0.03mm | ±0.03mm | ±0.03mm | ±0.05mm | ±0.05mm | ±0.1mm | ±0.02mm | ±0.03mm | ±0.03mm | ±0.05mm | ±0.05mm | |
| Degrees of freedom | 6 | | | | | | 6 | | | | | |
| Control box size | 536*445*319mm | | | | | | 536*445*319mm | | | | | |
| End I/O port | Digital input: 3, digital output: 3, analog input: 2 | | | | | | Digital input: 3, digital output: 3, analog input: 2 | | | | | |
| Control box I/O port | Digital input: 16, digital output: 16, analog input: 2, analog output: 2 | | | | | | Digital input: 16, digital output: 16, analog input: 2, analog output: 2 | | | | | |
| I/O source | 24V 2A | | | | | | 24V 2A | | | | | |
| Communication | TCP/IP and Modbus | | | | | | TCP/IP and Modbus | | | | | |
| Programming | Graphical programming, remote call interface | | | | | | Graphical programming, remote call interface | | | | | |
| IP rating | IP54 | | | | | | IP66 | | | | | |
| Collaborative operation | 10 advanced security configuration functions | | | | | | 10 advanced security configuration functions | | | | | |
| Main material | Aluminum alloy | | | | | | Aluminum alloy | | | | | |
| Working temperature | 0-50°C | | | | | | 0-50°C | | | | | |
| Power input | 200-240V AC, 50-60Hz | | | | | | 200-240V AC, 50-60Hz | | | | | |
| Cable | Cable to the control box: 5 m, cable to the teach pendant: 5 m | | | | | | Cable to the control cabinet: 5 m, cable to the teach pendant: 5 m | | | | | |

Drawing

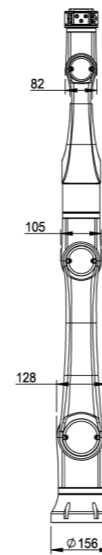
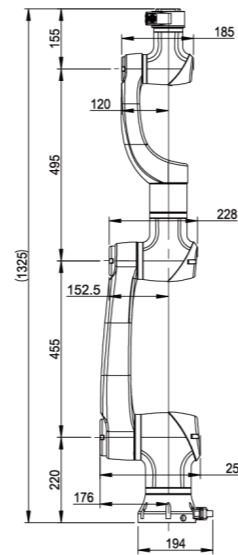
E03



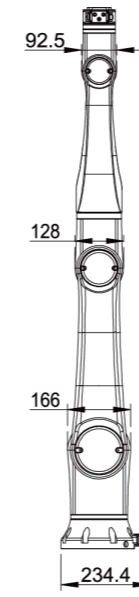
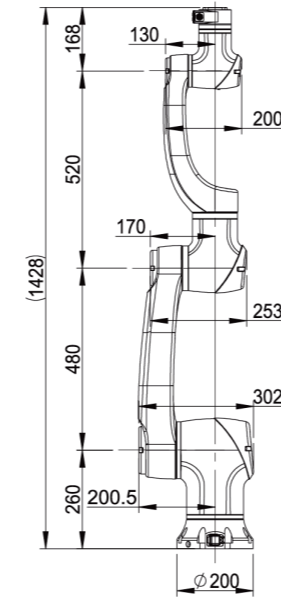
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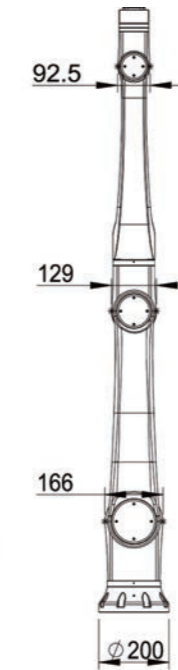
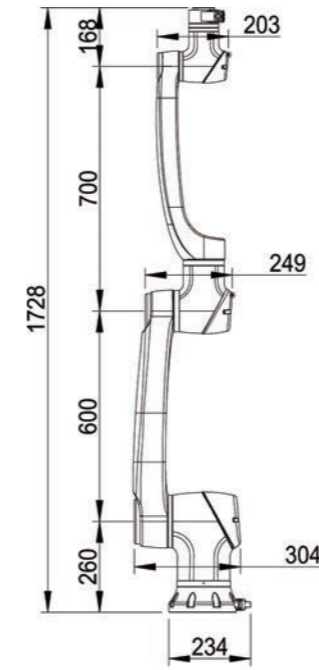
E05-L



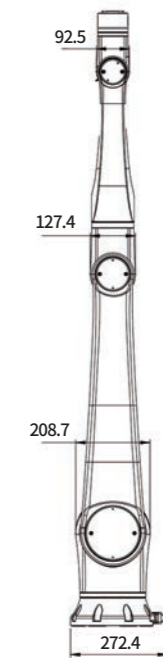
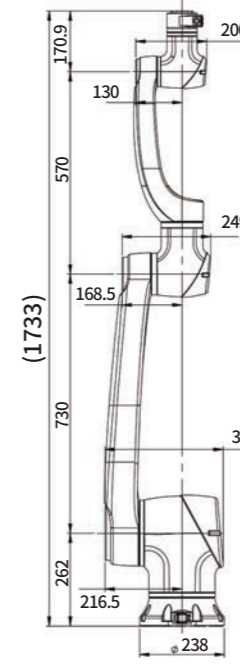
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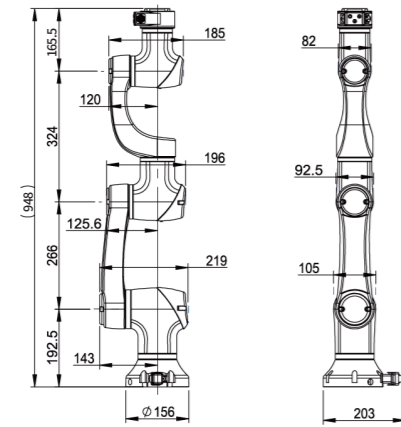
E10-L



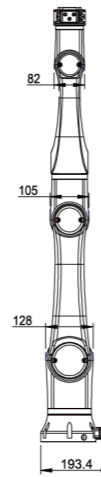
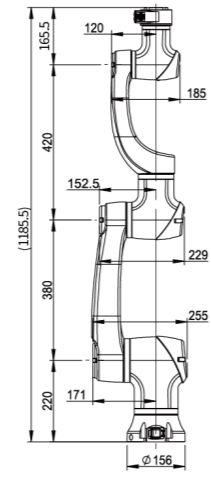
E15



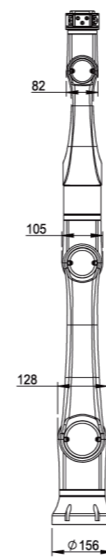
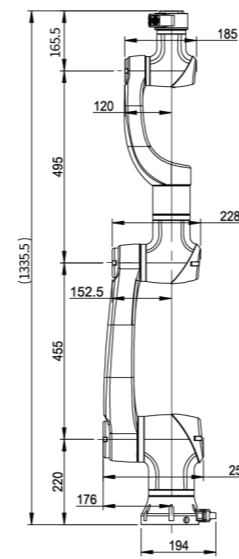
P03



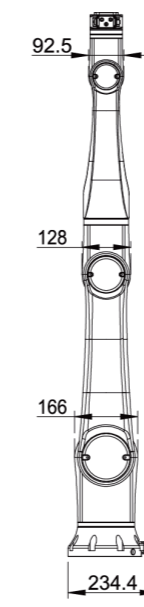
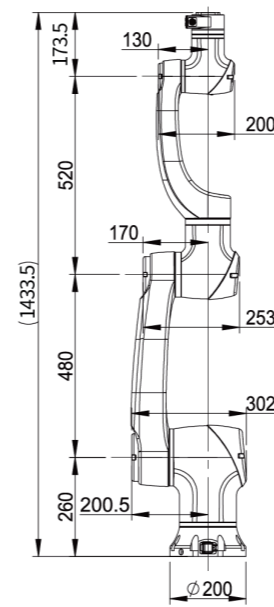
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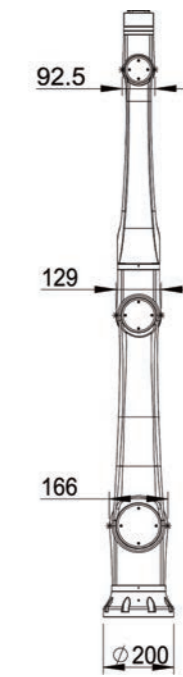
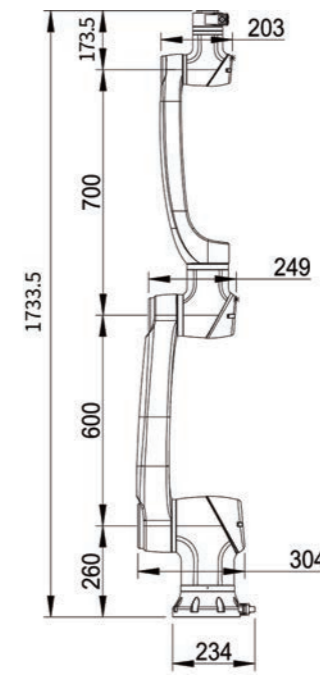
P05-L



P10



P10-L





Han's Robot Product Details →



Elfin
Collaborative
Robot



Elfin-P
Collaborative
Robot



FR
Multi-sensing
Autonomous
Vehicle



STAR
Compound
Robot

Han's Robot Products/First-Generation 6-Axis Collaborative Robot

Elfin Collaborative Robot

Overview

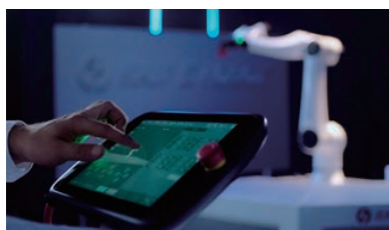
The Elfin 6-axis collaborative robot can be used in automated integrated production lines, assembly, picking, welding, grinding, spraing and other applications, and have been exported to more than 100 countries and regions. It adopts a unique double-joint module design, where one motion module contains two joints to form a unique kinematic structure, which not only differs from most collaborative robots in the market, but also provides more flexibility when working.



Why Elfin

Optimized Singularity

The unique arm design not only avoids the product homogeneity, but also reduces the singularity.



First dual-joint module design in China

The unique kinematic design enables the robot to have high flexibility. The highly integrated modular design minimizes the arm weight.



Highly Flexibility 6-DOF collaborative robot

The collaborative robot with 4/6-axis coaxial structure has almost reached the flexibility of 7-DOF robots



Modularity

All-in-one module of fully self-developed reducer, motor, encoder, drive and software



Industries

- Electronics
- Automotive
- Metal processing
- Semiconductor
- Education and research

Applications

- Loading and unloading
- Assembly
- Picking
- Welding
- Palletizing
- Glue dispensing
- Inspecting

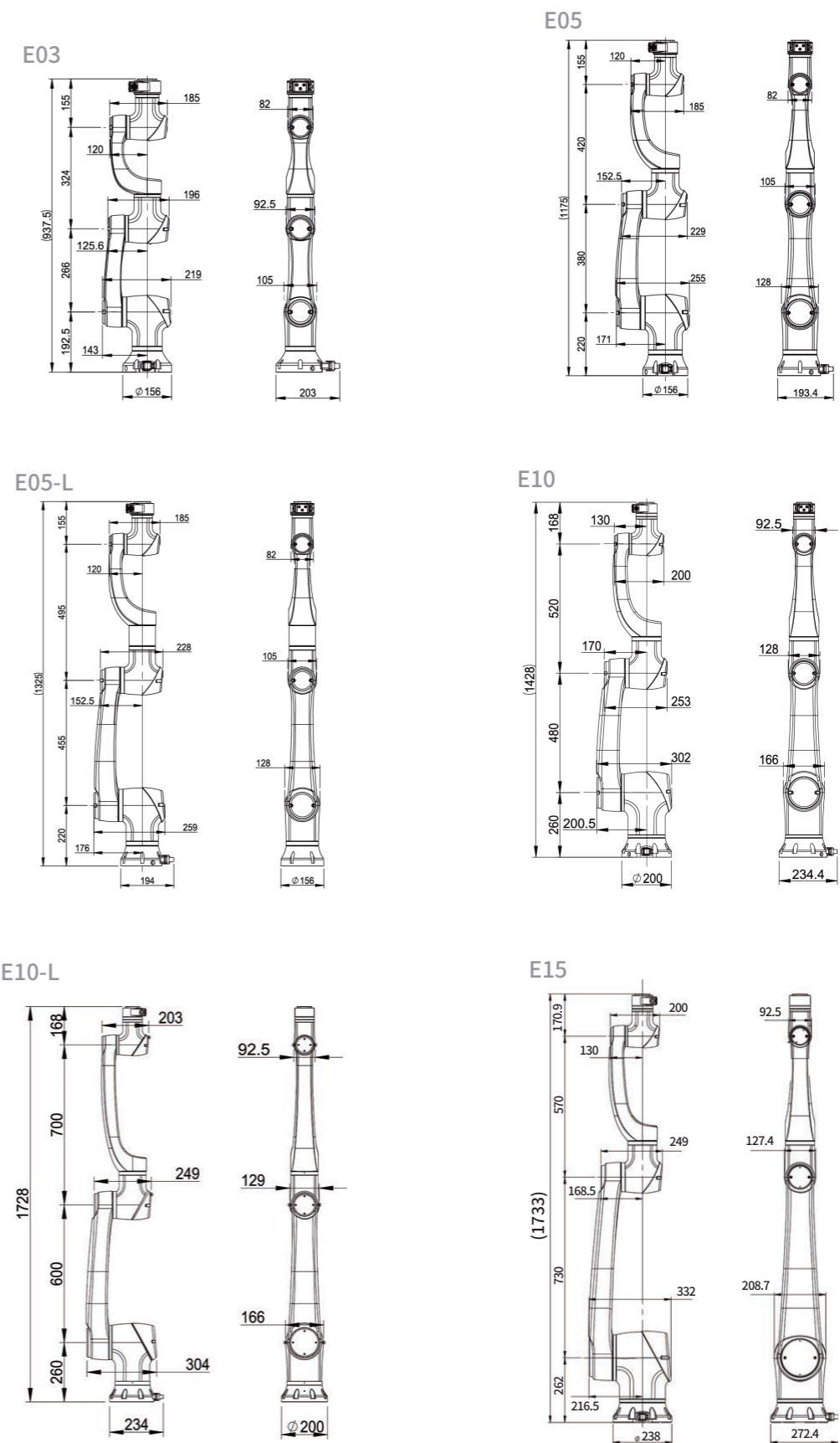
Joint motions:



Technical Specifications

| Model | E03 | E05 | E05-L | E10 | E10-L | E15 |
|-------------------------|--|------------------------------|------------------------------|--|--|---|
| Weight | 18kg | 25kg | 26kg | 43kg | 45kg | 60kg |
| Payload | 3kg | 5kg | 3.5kg | 10kg | 8kg | 15kg |
| Reach | 590mm | 800mm | 950mm | 1000mm | 1300mm | 1300mm |
| Power consumption | 100W typical application | 180W typical application | 180W typical application | 350W typical application | 350W typical application | 600W typical application |
| Joint range | ±360° | | | | | |
| Joint speed | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s | J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s | J1-J2 80°/s J3-J4 120°/s J5-J6 150°/s |
| Tool speed | 2m/s | | | | | |
| Repeatability | ±0.03mm | ±0.03mm | ±0.03mm | ±0.05mm | ±0.05mm | ±0.1mm |
| Degree of freedom | 6 | | | | | |
| End I/O port | Digital input: 3, digital output: 3, analog input: 2 | | | | | |
| Control box I/O port | Digital input: 16, digital output: 16, analog input: 2, analog output: 2 | | | | | |
| I/O Source | 24V 2A | | | | | |
| Communication | TCP/IP and Modbus | | | | | |
| Programming | Graphical programming, remote call interface | | | | | |
| IP classification | IP54 | | | | | |
| Collaborative operation | 10 advanced security configuration functions | | | | | |
| Main material | Aluminum alloy | | | | | |
| Working temperature | 0-50°C | | | | | |
| Power input | 200-240V AC, 50-60Hz | | | | | |
| Cable | Cable to the control box: 5m; cable to the teach pendant: 5m | | | | | |

Drawing



Control box

| | |
|---------------------|--|
| Dimensions | 445.2mm x 318.8mm x (360+176)mm |
| Stand height | 176mm |
| Weight | 18.5kg |
| Power output | 48V DC |
| Working temperature | 0~50°C |
| Working Humidity | 90% relative humidity (non-condensing) |
| IP classification | IP20 |



Teach pendant

| | |
|-------------------|------------------------------|
| Dimensions | 327 mm x 230 mm x (45+22) mm |
| Weight | 2.7kg (include cable) |
| Display | 10.4" |
| Resolution | 1024 x 800 |
| E-stop button | 1 |
| IP classification | IP54 |

Han's Robot Products/Second-Generation 6-Axis Collaborative Robot

Elfin-P Collaborative Robot

Overview

Elfin-P is a lightweight 6-axis collaborative robot developed based on Elfin that can be used in automated integrated production lines, assembly, picking, welding, grinding, spraying, dispensing, inspecting and other applications. The high repeatability and protection rating ensures it can be used freely in complex working environments.



Why Elfin-P

Higher protection rating

IP66 protection rating is designed to be dust-proof and waterproof, ensuring that it can be used freely in harsh environments such as oil and moisture



Faster response

The EtherCAT communication between the controller and each joint enables real-time control of the refresh frequency of 1000Hz for industry-leading trajectory accuracy control



Stronger anti-interference ability

Stronger electromagnetic compatibility, which ensures that the robot can still operate properly in a strong electromagnetic interference environment



Industries

- Electronics
- Automotive
- Semiconductor
- Metal processing
- Education and research

Applications

- Loading and unloading
- Assembly
- Picking
- Welding
- Palletizing
- Dispensing
- Inspecting

Joint motions:



Technical Specifications

| Type | P03 | P05 | P05-L | P10 | P10-L |
|-------------------------|--|------------------------------|------------------------------|--|--|
| Weight | 19kg | 26kg | 27kg | 45kg | 48kg |
| Payload | 3kg | 5kg | 3.5kg | 10kg | 8kg |
| Reach | 590mm | 800mm | 950mm | 1000mm | 1300mm |
| Power consumption | 100W typical application | 180W typical application | 180W typical application | 350W typical application | 350W typical application |
| Joint range | ±360° | | | | |
| Joint speed | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J4 180°/s J5-J6 200°/s | J1-J2 120°/s J3-J4 135°/s J5-J6 180°/s | J1-J2 100°/s J3-J4 135°/s J5-J6 180°/s |
| Tool speed | 2m/s | | | | |
| Repeatability | ±0.02mm | ±0.03mm | ±0.03mm | ±0.05mm | ±0.05mm |
| Degree of freedom | 6 | | | | |
| End I/O port | Digital input: 3, digital output: 3, analog input: 2 | | | | |
| Control box I/O port | Digital input: 16, digital output: 16, analog input: 2, analog output: 2 | | | | |
| I/O source | 24V 2A | | | | |
| Communication | TCP/IP and Modbus | | | | |
| Programming | Graphical programming, remote call interface | | | | |
| IP classification | IP66 | | | | |
| Collaborative operation | 10 advanced security configuration functions | | | | |
| Main material | Aluminum alloy | | | | |
| Working temperature | 0-50°C | | | | |
| Power input | 200-240V AC, 50-60Hz | | | | |
| Cable | Cable to the control cabinet: 5m; cable to the teach pendant: 5m | | | | |



Control box

| | |
|---------------------|--|
| Dimensions | 445.2mm x 318.8mm x (360+176)mm |
| Stand height | 176mm |
| Weight | 18.5kg |
| Power output | 48V DC |
| Working temperature | 0~50°C |
| Working Humidity | 90% relative humidity (non-condensing) |
| IP classification | IP20 |

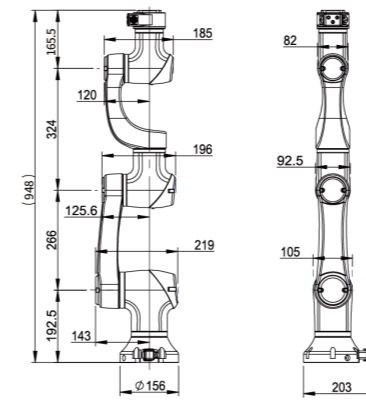


Teach pendant

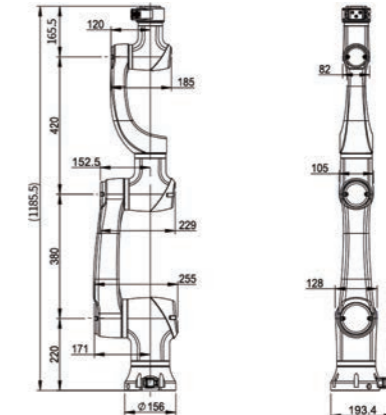
| | |
|-------------------|------------------------------|
| Dimensions | 327 mm x 230 mm x (45+22) mm |
| Weight | 2.7kg (include cable) |
| Display | 10.4" |
| Resolution | 1024 x 800 |
| E-stop button | 1 |
| IP classification | IP54 |

Drawing

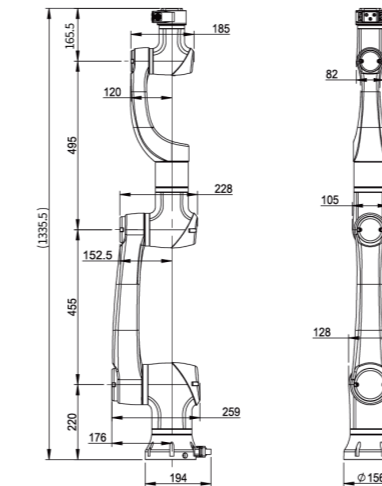
P03



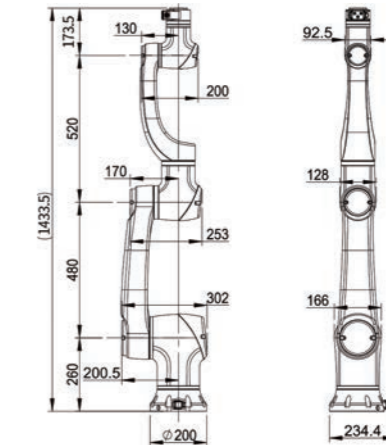
P05



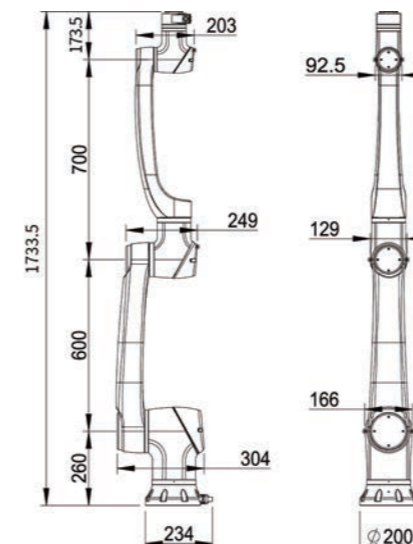
P05-L



P10



P10-L



Han's Robot Products/Automated Guided Vehicle

FR Multi-sensing Autonomous Vehicle

Features

Overview

FR is a new generation of multi-sensing autonomous vehicles from Han's Robot, used for indoor intralogistics tasks. It can autonomously transport items and navigate freely in its environment. As a mobile robot, it makes the labor of the workers easier and improves business efficiency. This robot is also equipped with obstacle avoidance radar, which can work continuously and safely without interruption. Moreover, it has built-in autonomous navigation system and dispatching software, which enable multiple FR to serve simultaneously, keep the production running and maintain the flexibility of its manipulation.



Payload 200kg / 1200 kg



High speed charging and long endurance



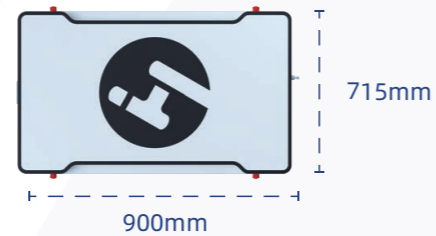
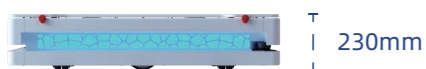
MAX Speed 1.5 m/s



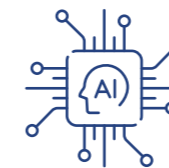
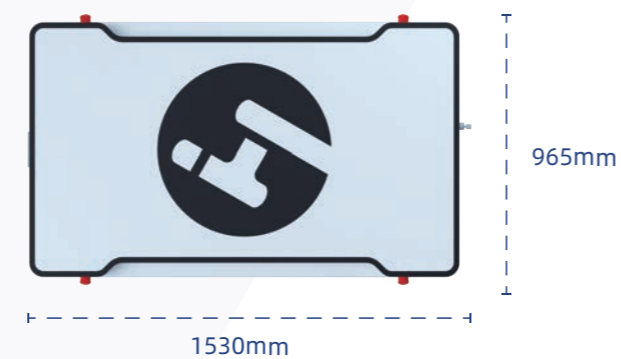
3D Visual Sensor (optional)

Dimensions

FR-200
200kg
46AH



FR-1200
1200kg
125AH



Artificial Intelligence
Path Optimization, Smart Interaction

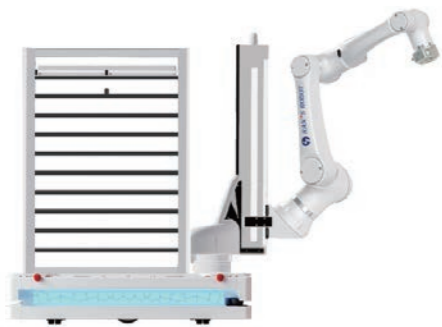


Safe Human Detection
Touchless Sensor Technology



Status Visualization
LED lights can show the robot's working status

Expand application



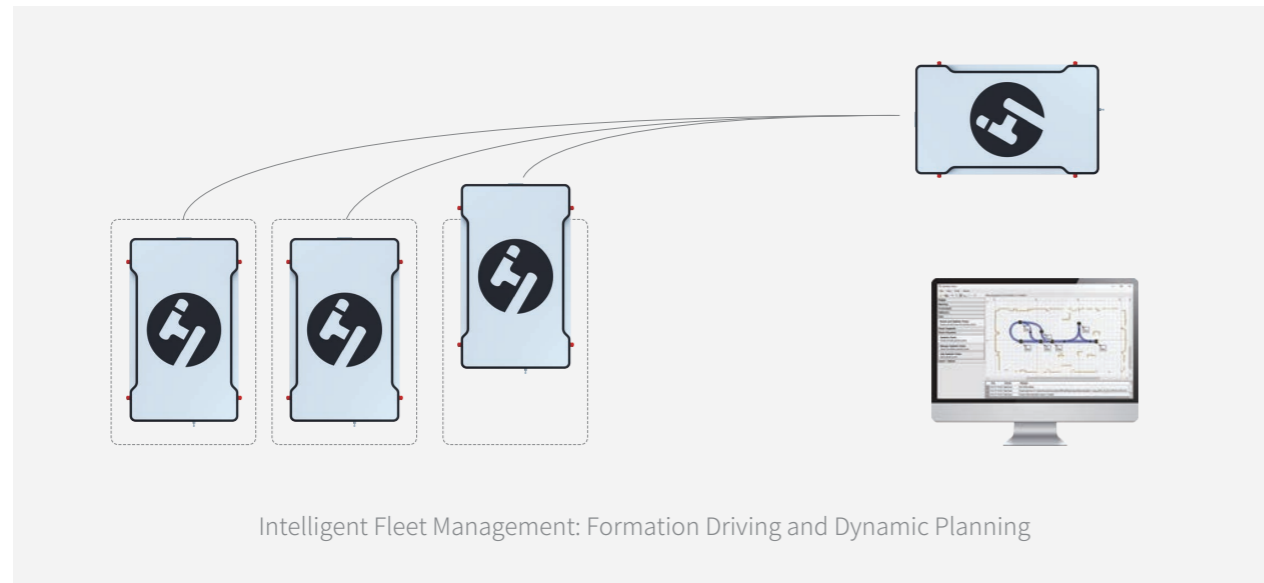
FR+Elfin-P



FR for Logistics



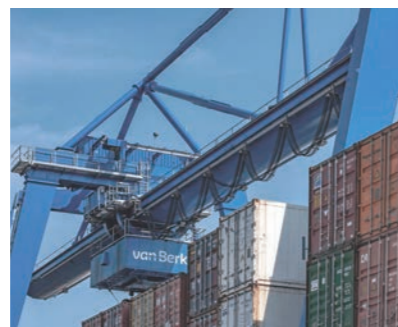
FR+Elfin



Recommended Industries



Healthcare



Logistics



3C Products

Tech specs

| | Model | FR-200 | FR-1200 |
|------------------------|---------------------------|---|--|
| Basic parameters | Payload | 200 kg | 1200 kg |
| | MAX Loading Current | 20A | 95A |
| | Actuation | Differential Drive | |
| | MAX Velocity | 1.5 m/s | |
| | Communication Interface | TCP/IP , Modbus | |
| | Outbound Interface | WiFi , 1 x RJ45 | |
| | IP Classification | IP54 | |
| | Weight | (100/120) kg(without / with lifting units) | (280/310) kg(without / with lifting units) |
| | Dimensions | L900×W715×H230(mm) | L1530×W965×H310(mm) |
| | Positioning Accuracy | ±10mm | |
| | Safety Laser Scanner 360° | PLd/ Category 3 (ISO 13849- 1) | |
| | Navigation Mode | Laser SLAM | |
| | Battery parameters | Lifting Units | 1x200kg , 1 x 0-60mm |
| Battery Voltage | | DC 48V | |
| Battery Capacity | | 46AH | 125AH |
| Charging Voltage | | AC220V , 50-60Hz | |
| Charging Time | | 2hrs (Automated) / 1.5hrs(Manual) | 2.5hrs (Automated) / 2hrs(Manual) |
| Running Time (no load) | | 15hrs | 24hrs |
| Charging Mode | | Automated / Manual | |
| Sensor | Vision (optional) | RealSense – D415 Camera | |
| | Safety | Touchless Safe Human Detection Safety Scanners | |
| Software | Operating Software | Robot application software / Dispatching software | |
| | Open Architecture | AGV API | |
| | Safety Features | Safe Human Detection, Safe Speed Control | |
| Programming Features | Human-Robot-Interaction | Motion tracking, PC based GUI | |
| | Environment Visualization | Dynamic Mapping (SLAM) | |
| | Fleet Management | Formation Driving, Fleet Monitoring Tool | |
| Others | Warranty | 12 months | |

Han's Robot Products/Compound Robots

STAR Compound Robot

Overview

The STAR compound robot is an intelligent mobile robot, which combines the self-developed mechanical arm and mobile robot FR, vision system, gripper and other components to perform mobile operations to achieve functional applications such as grasping, handling, assembly, and detection of materials. According to the customer's on-site use environment, it can match the corresponding scheduling system for flexible scheduling and rapid deployment. The core units of the STAR are independently developed, with high cost performance and strong system scalability, which can connect to the customer's MES (or other systems) and provide rich solutions according to different needs of customers. It can serve the future intelligent manufacturing industry 4.0.

It is mainly used in industries (such as electronics, metal products, auto parts, electricity, new energy, ships, aerospace), healthcare, family services, file management and other applications.



Intelligent scheduling

Based on the self-developed architecture and intelligent planning algorithm, the large-scale scheduling of robots is realized to ensure the efficient operation of the system.



Strong Scalability

It efficiently connects to the enterprise's MES/WMS information system and can quickly install application function modules according to requirements.



Intelligent obstacle avoidance

Equipped with sensors such as lidar and visual camera (optional), it can intelligently identify obstacles, actively park and avoid obstacles.



Stable performance

With independent development of core components, it shows the perfect combination of body and arm, and the performance is more stable.



Automatic lifting

The internal materials are automatically lifting, which can maximize the use of body space, store more materials in a limited space, and reduce material transfer.

Features



Rapid Deployment

Based on the SLAM navigation technology, without the scene transformation, the environment map is automatically generated, the scheduling planning service is realized, and the deployment is fast.



Self-check

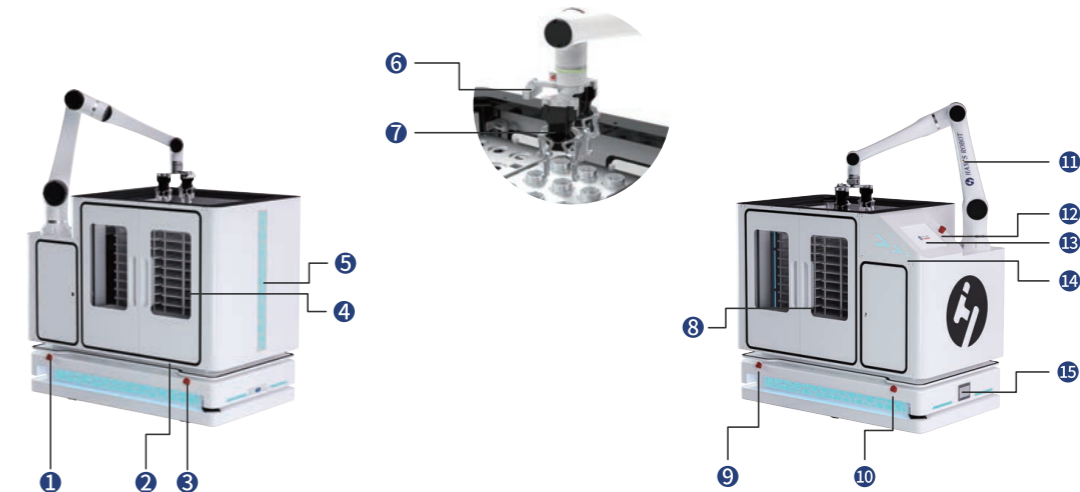
It can obtain the robot hardware and operating status in real time, which realizes self-check and fast fault diagnosis.



Automatic charging

The STAR can automatically go back to charging pile for recharging, which ensures the robot to achieve 7*24 all-day operation and high-frequency fast response between tasks.

Parts name



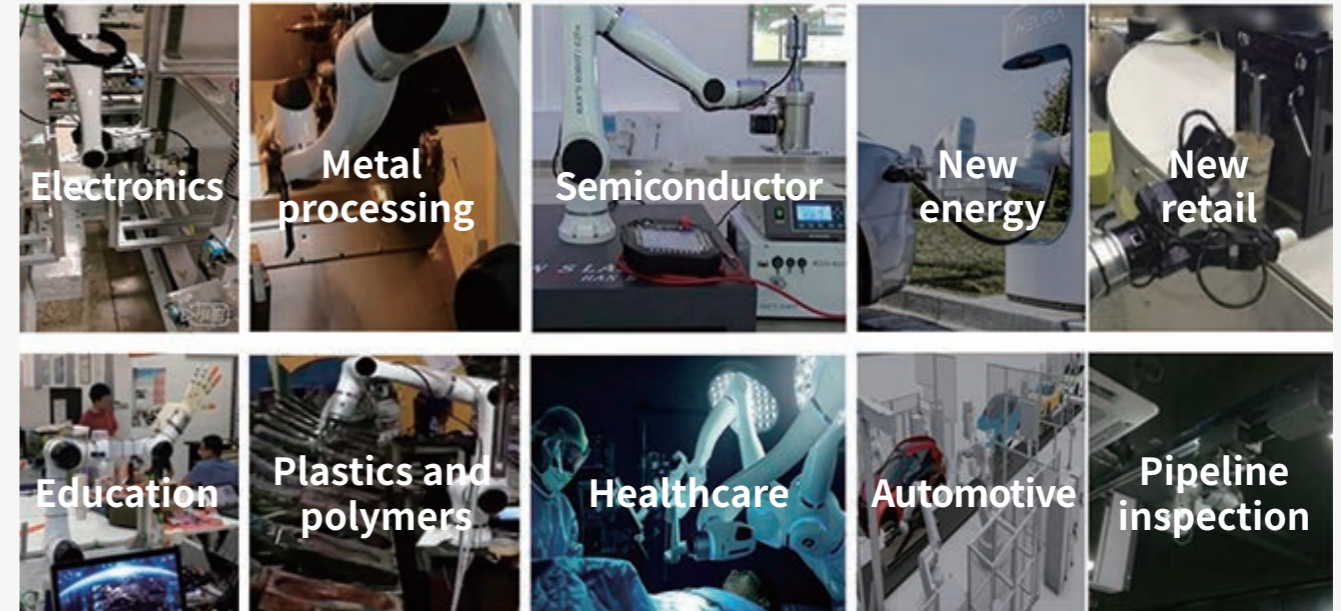
- E-STOP 1 3 9 10 12
- Drainage Outlet 2
- Lifting Unit 1 (To Be Processed) 4
- Single Lights 5 14
- 3D Camera 6
- Electric Gripper 7
- Lifting Unit 2 (Finished Product) 8
- E10-L (Optional) 11
- 12" Touchscreen 13
- FR 15

Technical Specifications

| Model | STAR-L | STAR-H | |
|-----------------------|----------------------------------|--|-----------------------------------|
| Main body | Robot | E03 / E05 | E10-L |
| | Vehicle | FR-200 (payload 200kg) | FR-1200 (payload 1.2t) |
| Basic performance | Dimensions (Elfin Not Included) | L900×W715×H950(mm) | L1530×W965×H1304(mm) |
| | Weight (Shelf Included) | 200kg | 900kg |
| | MAX Payload | 100kg | 600kg |
| | Lifting Unit (Customizable) | 10 Layers,15 PCS/Layer | |
| Running performance | MAX Velocity | 1.5m/s | |
| | Navigation Mode | Laser SLAM | |
| | Actuation | Differential Drive | |
| Vision performance | Vision (Standard Mode) | Camera (Customizable) | |
| | Positioning Accuracy | ±0.5mm | |
| Software | Operating Software | Robot application software / Dispatching software (optional) | |
| | Development Platform | IPC ubuntu 20 | |
| Endurance performance | Battery Voltage | DC 48V | |
| | Battery Capacity | 46AH | 125AH |
| | Running Time (with load) | 8hrs | 12hrs |
| | Charging Mode | Automated / Manual | |
| | Charging Time | 2hrs (Automated) / 1.5hrs(Manual) | 2.5hrs (Automated) / 2hrs(Manual) |
| External Interface | Standard Communication Interface | TCP/IP, Modbus | |
| | Outbound Interface | WiFi,1 x RJ45 | |



Han's Robot Applications

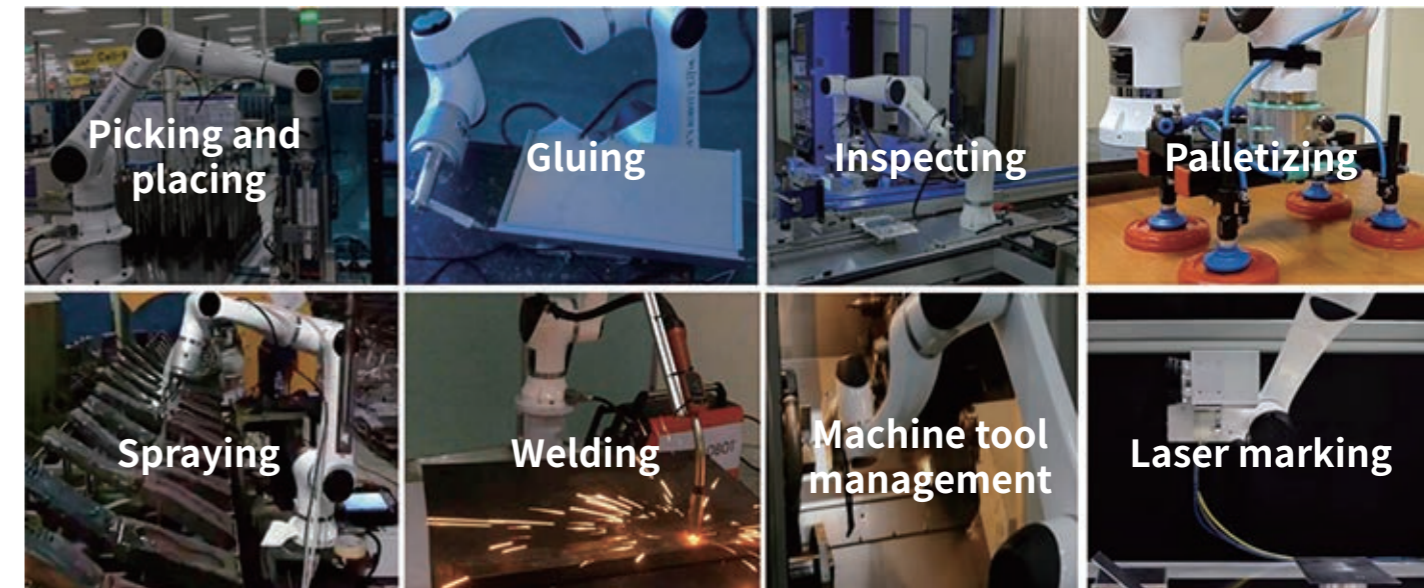


↑ Industry applications:

Han's Robot collaborative robots have been widely used in electronics, automotives, semiconductors, metal processing, new energy, pipeline inspection and other fields. Han's Robot uses robot technologies for collaboration in global intelligent manufacturing, which promotes productivity in all walks of life.

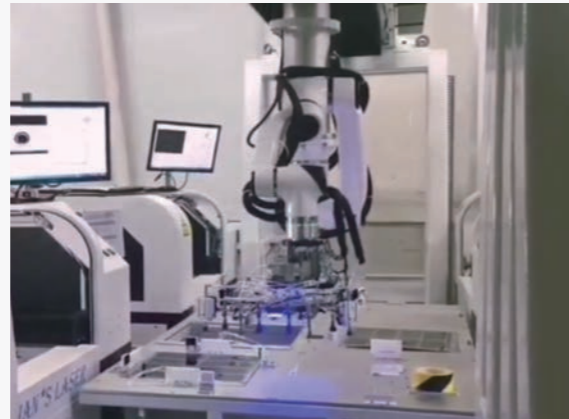
↓ Process applications:

Loading and unloading, welding, marking, assembling, polishing, handling, inspecting, gluing, picking, screwing, etc.



Electronics manufacturing industry Laser cutting

One robot is used for loading and unloading for four laser cutting machines at the same time. The four cutting machines are placed in pairs, and a 7-axis guide rail is used in the middle to realize the motion of the collaborative robot between the machines. A vision camera is integrated to the robot to realize the positioning for loading and unloading as the required unloading precision of the laser cutting machine is about 0.1 mm.



Space-Saving **Easy to operate**

The overall layout is compact which occupies a small area, and there is no need to do great changes to the original plant. Moreover, the equipment deployment is easy.

It is easy to operate the collaborative robots. Customers can switch products or debug new products by themselves after simple training, which greatly reduces the cost of product replacement.

More scenarios: loading and unloading, inspecting, grinding, spraying, assembling, marking, etc.

Healthcare industry Remote ultrasound diagnosis and treatment

The remote ultrasonic diagnosis and treatment robot realizes remote consultation of experts in different places by using teleoperation technologies, which meets the increasingly demand for diagnosis resources in the grassroots hospitals.

Precision: The robot accurately reproduces the doctor's operating position and strength, which ensures the quality of ultrasound imaging;

Friendly: Gentle motion control, real-time pressure tracking control, to achieve a friendly patient experience comparable to professional examination methods;

Safe: Ensure the safety of human-computer interaction through high-level safety functions such as robot motion area limitation, inspection pressure protection, and collision protection;

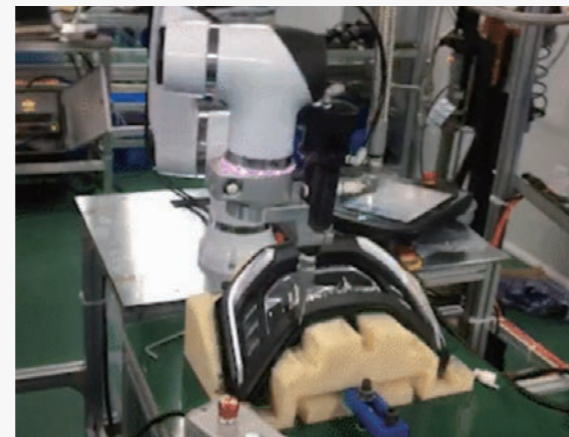
Efficient: High-speed remote communication realizes high-definition ultrasound image transmission, and remote real-time control of robotic arms, which ensures the efficiency and precision of doctors' diagnosis;



More scenarios: drug packaging, test tube pickup and placing, sterilization, testing, surgical assistance, etc.

Automotive manufacturing industry Gluing for car lights

By adopting one-to-two structure integration, one cold glue device supplies can glue for two collaborative robots. The double-station free gluing improves the gluing efficiency and quality and avoids the impact on the personnel health, which greatly reduces labor and equipment costs.



Safe and flexible **Energy saving and low consumption**

High-precision linear gluing, harmless operation, improved yield rate.

The cold glue does not require heating, which greatly reduces energy consumption.

More scenarios: loading and unloading, spraying, assembling, inspecting, picking, marking, etc.

Hybrid robot CNC loading and unloading

In this case, the composite robot moves intelligently in the same workshop to support multiple production links: CNC production workshop material transfer project Automatic loading and unloading items of materials

Case features

Han's robot 6-axis collaborative robot + intelligent mobile robot, with its large capacity and automatic lifting mechanism, can load more materials at one time, freely shuttle in the workshop, ensure the normal operation of multiple equipment in the workshop, and help customers to automate production needs



More scenarios: warehousing, packaging, assembling, testing, pickup, etc.

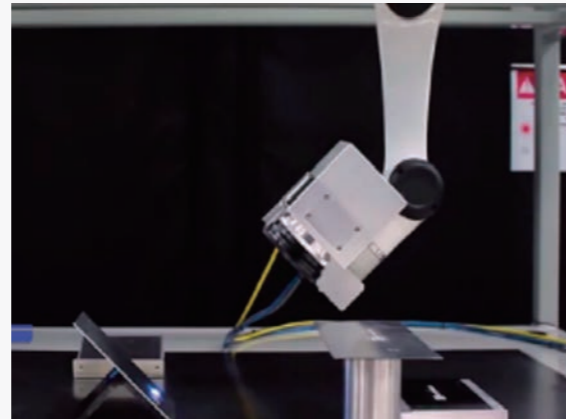
Metal processing industry Laser Marking

Han's marking robots can realize multi-directional automatic marking, from loading and unloading to marking, which meets the unmanned, automated, and flexible use requirements, improves the delivery efficiency, and reduces production costs.

Flexible and efficient Easy to operate

Realize flexible, efficient, multi-angle, multi-material free marking.

Graphical programming and robot program editing are simple and easy.



More scenarios: marking, rust removal, grinding, screwing, welding, etc.

Sanitary industry Spin welding

Solve the pain points of ultrasonic welding with high noise and inconsistent manual feeding pace. Less labor and higher efficiency, easy to operate, stable robot production.



More scenarios: visual grasping, gate polishing, assembling, picking and placing, hot plate welding, loading and unloading, etc.

Semiconductor Industry Wafer handling

Han's hybrid robots interwork with wafer processing equipment to provide MES whole-factory automated wafer handling solutions, and fully independent IPR upper-computer scheduling system and planning.

Fast and robust

One robot is connected to five wafer processing devices for loading and unloading, and the efficiency is 68% higher than manual operation. The fully automated black light factory works automatically in a controllable manner. Multiple devices can be independently scheduled in 24-hour operation.



More scenarios: lithography, cleaning, etching, precipitation, equipment care, grinding, etc.

Pipeline inspection industry Pipeline equipment inspection

In this application, Han's Robot is integrated with various sensors to realize 24-hour visual automatic inspection in the pipeline. The 6-DOF joint design allows the robot to be better planned for complex motion paths, increases the monitoring scope and precision, and achieves no-blind-angle monitoring.

Diverse applications Less risks

Used in power, energy, petroleum, transportation, smart buildings, etc.

Less safety risks and labor costs compared with traditional manual inspections



More scenarios: electricity, energy, construction, transportation, minerals, marine

Education industry

VR training

1. VR industrial robot task training system based on virtual reality. It realizes multi-brand, multi-robot, multi-scene robot task operation training, including robot welding training, robot spraying training, robot casting training, robot palletizing training, robot loading and unloading training, and robot mobile phone assembly training.

2. Learn and master the operations of industrial robots through the VR robot system, and practical training of physical collaborative robots, which further deepens and consolidates the basic knowledge and skill training results of industrial robots, and greatly improves the teaching and training effects.



More scenarios: teaching platform, cyclic assembly line, mobile robot application, SCARA application, laser marking robot loading and unloading workstation, disassembly and installation of collaborative robot, robot integrated standard workstation

New retail industry

Milk tea robot

In this application, a new tea flagship store uses Han's robots in the beverage production area to collaborate in tea making, blending, and delivery, which adds value (such as freshness, attractiveness, and customer experience) to its service and image and greatly speeds up beverage production.

Fresh experience

One-click self-service, widely used in airports, hotels, restaurants, stations, shopping malls, and other places

Save kitchen labor

Less labor and higher efficiency, easy operation, convenient maintenance, short time period of cost recovery



More scenarios: massage, coffee latte, unmanned sales, etc.