



ADR-B SERIES

- Direct drive brushless motor
- Fully integrated with encoder and bearing
- Low cogging torque
- Precise homing through index pulse
- Low speed and high speed windings

UK & Ireland Official Distributor



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ADR110-B113

ADR110-B113				
Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C①	T _{Cn}	Nm	1.9	1.9
Peak Torque	T _{Pk}	Nm	5.8	5.8
Torque Constant ±10%	K _t	Nm/Arms	0.65	0.32
Back EMF constant ±10%	K _e	Vpeak/rpm	0.055	0.028
Motor Constant @25°C	K _m	Nm/Sqr(W)	0.30	0.30
Resistance (L-L) @25°C ±10%②	R ₂₅	Ω	3.20	0.80
Inductance (L-L) ±20%③	L	mH	17.15	4.29
Electrical time constant	τ _e	ms	5.36	5.36
Continuous Current @100°C④	I _{Cn}	Arms	3.0	6.0
Peak Current	I _{Pk}	Arms	9.0	18.0
Continuous Power Dissipation @100°C⑤	P _{Cn}	W	55.7	55.7
Max. Coil Temperature	T _{max}	°C	100.0	100.0
Thermal Dissipation Constant⑥	K _{thn}	W/°C	0.7	0.7
Max. Bus Voltage	U _{bus}	Vdc	600.0	600.0
Pole Number	p	-	16	16
Rec. Max Speed @230V AC⑦	Ω _{max}	rpm	1700	2000
Mechanical Parameters				
Overall Mass	m _n	kg	3.20	3.20
Rotor Inertia	J _r	kg·m ²	3.086E-04	3.086E-04
Axial Runout⑧	-	μm	15	15
Radial Runout⑨	-	μm	15	15
Max Axial Load (Upright Mounting)⑩	-	N	439	439
Max Axial Load (Inverted / Wall mounting)	-	N	35	35
Max Moment Load (Upright Mounting)	-	Nm	25	25
Max Moment Load (Inverted / Wall Mounting)	-	Nm	2.8	2.8
Encoder Parameters				
ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	3005	3005
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	240400	240400
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	480800	480800
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	1202000	1202000
Accuracy with Error Mapping⑪	-	arc sec	+/-5.4	+/-5.4
Repeatability⑫	-	arc sec	+/-2.7	+/-2.7
Other Information				
Insulation Class	Class B (130°C)			
Protection Grade	IP40			
Compliance with Global Standards	RoHS, CE, UL (option)			
Ambient Temperature	Operation	0°C to 40°C (non-freezing)		
	Storage	-15°C to 70°C (non-freezing)		
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)		
	Storage	10%RH to 90%RH (non-condensing)		
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.			

① Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.

② Resistance is measured by DC current with standard 3 m cable.

③ Inductance is measured by current frequency of 1 kHz.

④ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.

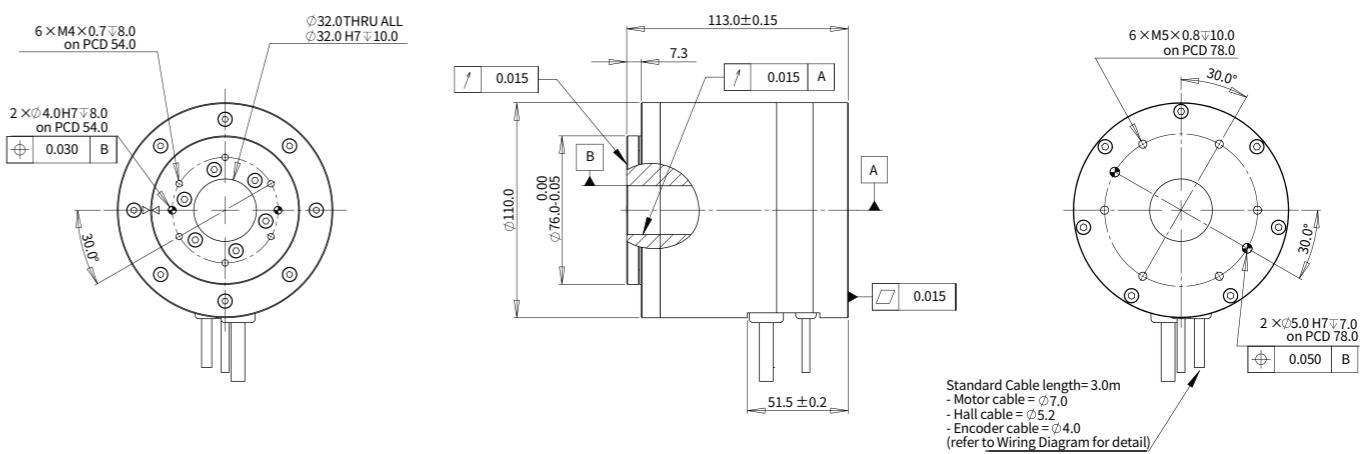
⑤ The runout value in parenthesis is optional.

⑥ Please refer to the illustration for different mountings.

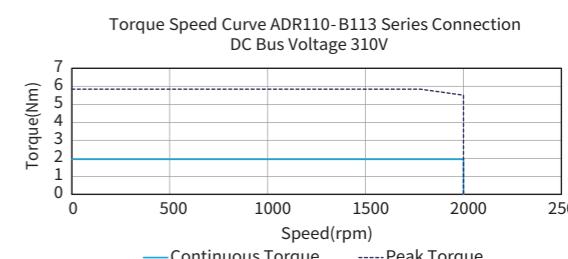
⑦ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.

The contents of datasheet are subjected to change.

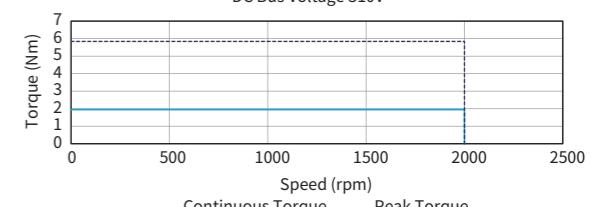
Dimension



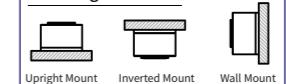
Torque-Speed Curve



Torque Speed Curve ADR110-B113 Parallel Connection DC Bus Voltage 310V



Mounting Illustration

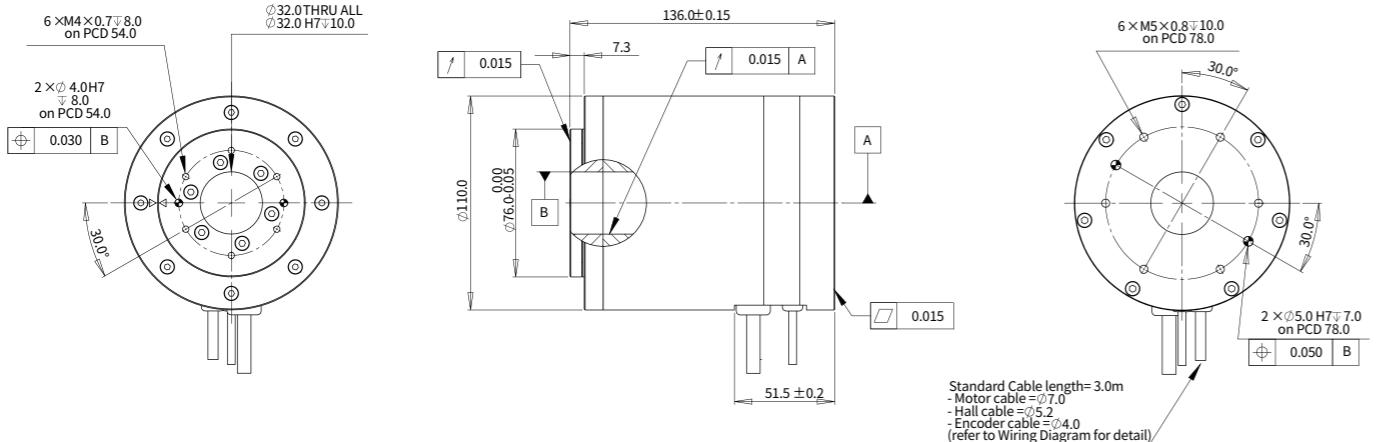


ADR110-B136

ADR110-B136				
Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C ①	T _c n	Nm	4.2	4.2
Peak Torque	T _p k	Nm	12.6	12.6
Torque Constant ±10%	K _t	Nm/Arms	1.40	0.70
Back EMF constant ±10%	K _e	Vpeak/rpm	0.119	0.060
Motor Constant @25°C	K _m	Nm/Sqrt(W)	0.51	0.52
Resistance (L-L) @25°C ±10% ②	R ₂₅	Ω	4.90	1.21
Inductance (L-L) ±20% ③	L	mH	26.26	6.49
Electrical time constant	T _e	ms	5.36	5.36
Continuous Current @100°C ④	I _c n	Arms	3.0	6.0
Peak Current	I _p k	Arms	9.0	18.0
Continuous Power Dissipation @100°C ⑤	P _c n	W	85.3	84.2
Max. Coil Temperature	T _{max}	°C	100.0	100.0
Thermal Dissipation Constant ⑥	K _{thn}	W/C	1.1	1.1
Max. Bus Voltage	U _{bus}	Vdc	600.0	600.0
Pole Number	p	-	16	16
Rec. Max Speed @230V AC ⑦	Ω _{max}	rpm	1000	2000
Mechanical Parameters				
Overall Mass	m _n	kg	4.60	4.60
Rotor Inertia	J _r	kg·m ²	4.419E-04	4.419E-04
Axial Runout ⑧	-	μm	15	15
Radial Runout ⑨	-	μm	15	15
Max Axial Load (Upright Mounting) ⑩	-	N	439	439
Max Axial Load (Inverted / Wall mounting)	-	N	35	35
Max Moment Load (Upright Mounting)	-	Nm	25	25
Max Moment Load (Inverted / Wall Mounting)	-	Nm	2.8	2.8
Encoder Parameters				
ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	3005	3005
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	240400	240400
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	480800	480800
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	1202000	1202000
Accuracy with Error Mapping ⑪	-	arc sec	+/-5.4	+/-5.4
Repeatability ⑫	-	arc sec	+/-2.7	+/-2.7
Other Information				
Insulation Class	Class B (130°C)			
Protection Grade	IP40			
Compliance with Global Standards	RoHS, CE, UL (option)			
Ambient Temperature	Operation	0°C to 40°C (non-freezing)		
	Storage	-15°C to 70°C (non-freezing)		
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)		
	Storage	10%RH to 90%RH (non-condensing)		
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.			

① Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.
 ② Resistance is measured by DC current with standard 3 m cable.
 ③ Inductance is measured by current frequency of 1 kHz.
 ④ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.
 ⑤ The runout value in parenthesis is optional.
 ⑥ Please refer to the illustration for different mountings.
 ⑦ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.
 The contents of datasheet are subjected to change.

Dimension

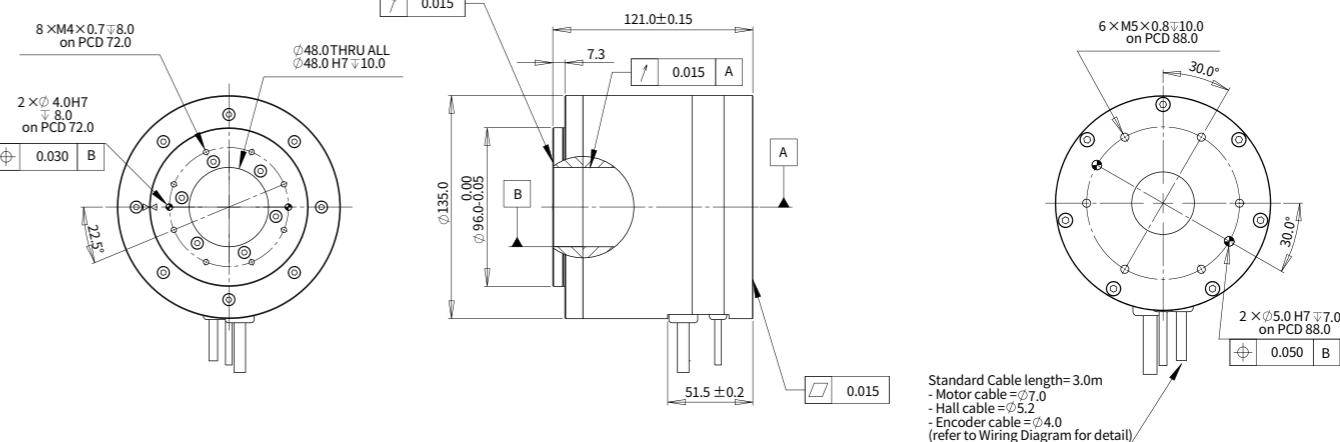


ADR135-B121

ADR135-B121				
Performance Parameters	Symbol	Unit	Series	Parallel
Continuous Torque @100°C ①	T _c n	Nm	5.2	5.2
Peak Torque	T _p k	Nm	15.5	15.5
Torque Constant ±10%	K _t	Nm/Arms	1.72	0.86
Back EMF constant ±10%	K _e	Vpeak/rpm	0.147	0.074
Motor Constant @25°C	K _m	Nm/Sqrt(W)	0.55	0.55
Resistance (L-L) @25°C ±10% ②	R ₂₅	Ω	6.60	1.65
Inductance (L-L) ±20% ③	L	mH	45.30	11.20
Electrical time constant	T _e	ms	6.86	6.79
Continuous Current @100°C ④	I _c n	Arms	3.0	6.0
Peak Current	I _p k	Arms	9.0	18.0
Continuous Power Dissipation @100°C ⑤	P _c n	W	114.9	114.9
Max. Coil Temperature	T _{max}	°C	100.0	100.0
Thermal Dissipation Constant ⑥	K _{thn}	W/C	1.5	1.5
Max. Bus Voltage	U _{bus}	Vdc	600.0	600.0
Pole Number	p	-	16	16
Rec. Max Speed @230V AC ⑦	Ω _{max}	rpm	630	1350
Mechanical Parameters				
Overall Mass	m _n	kg	3.90	3.90
Rotor Inertia	J _r	kg·m ²	9.916E-04	9.916E-04
Axial Runout ⑧	-	μm	15	15
Radial Runout ⑨	-	μm	15	15
Max Axial Load (Upright Mounting) ⑩	-	N	604	604
Max Axial Load (Inverted / Wall mounting)	-	N	56	56
Max Moment Load (Upright Mounting)	-	Nm	45	45
Max Moment Load (Inverted / Wall Mounting)	-	Nm	5.0	5.0
Encoder Parameters				
ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	4103	4103
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	328240	328240
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	656480	656480
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	1641200	1641200
Accuracy with Error Mapping ⑪	-	arc sec	+/-4	+/-4
Repeatability ⑫	-	arc sec	+/-2	+/-2
Other Information				
Insulation Class	Class B (130°C)			
Protection Grade	IP40			
Compliance with Global Standards	RoHS, CE, UL (option)			
Ambient Temperature	Operation	0°C to 40°C (non-freezing)		
	Storage	-15°C to 70°C (non-freezing)		
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)		
	Storage	10%RH to 90%RH (non-condensing)		
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.			

① Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.
 ② Resistance is measured by DC current with standard 3 m cable.
 ③ Inductance is measured by current frequency of 1 kHz.
 ④ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.
 ⑤ The runout value in parenthesis is optional.
 ⑥ Please refer to the illustration for different mountings.
 ⑦ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.
 The contents of datasheet are subjected to change.

Dimension



ADR220-B217

ADR220-B217

Performance Parameters		Symbol	Unit	Series	Parallel
Continuous Torque @100°C①		T _{Cn}	Nm	94.9	94.9
Peak Torque		T _{Pk}	Nm	284.6	284.6
Torque Constant ±10%		K _t	Nm/Arms	17.57	5.86
Back EMF constant ±10%		K _e	Vpeak/rpm	1.502	0.501
Motor Constant @25°C		K _m	Nm/Sqr(W)	4.47	4.37
Resistance (L-L) @25°C ±10%②		R ₂₅	Ω	10.32	1.20
Inductance (L-L) ±20%③		L	mH	106.70	11.90
Electrical time constant		T _e	ms	10.34	9.92
Continuous Current @100°C④		I _{Cn}	Arms	5.40	16.20
Peak Current		I _{Pk}	Arms	16.2	48.6
Continuous Power Dissipation @100°C⑤		P _{Cn}	W	581.9	608.9
Max. Coil Temperature		T _{max}	°C	100.0	100.0
Thermal Dissipation Constant⑥		K _{thn}	W/°C	7.8	8.1
Max. Bus Voltage		U _{bus}	Vdc	600.0	600.0
Pole Number		p	-	24	24
Rec. Max Speed @230V AC⑦		Ω _{max}	rpm	50	260
Mechanical Parameters					
Overall Mass	m _n	kg	23.4	23.4	
Rotor Inertia	J _r	kg·m ²	2.522E-02	2.522E-02	
Axial Runout⑧	-	μm	25	25	
Radial Runout⑨	-	μm	25	25	
Max Axial Load (Upright Mounting)⑩	-	N	1669	1669	
Max Axial Load (Inverted / Wall mounting)	-	N	105	105	
Max Moment Load (Upright Mounting)	-	Nm	85	85	
Max Moment Load (Inverted / Wall Mounting)	-	Nm	9.4	9.4	
Encoder Parameters					
ABI Optical Incremental Encoder (SIN/COS)	-	lines / rev	5071	5071	
ABI Optical Incremental Encoder Digital Resolution (80x)	-	counts / rev	405680	405680	
ABI Optical Incremental Encoder Digital Resolution (160x)	-	counts / rev	811360	811360	
ABI Optical Incremental Encoder Digital Resolution (400x)	-	counts / rev	2028400	2028400	
Accuracy with Error Mapping⑪	-	arc sec	+/-4	+/-4	
Repeatability⑫	-	arc sec	+/-2	+/-2	
Other Information					
Insulation Class	Class B (130°C)				
Protection Grade	IP40				
Compliance with Global Standards	RoHS, CE, UL (option)				
Ambient Temperature	Operation	0°C to 40°C (non-freezing)			
	Storage	-15°C to 70°C (non-freezing)			
Ambient Humidity	Operation	10%RH to 80%RH (non-condensing)			
	Storage	10%RH to 90%RH (non-condensing)			
Recommended Ambience	Indoor (no direct sunlight); No corrosive gas, inflammable gas, oil mist or dust.				

① Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment.

② Resistance is measured by DC current with standard 3 m cable.

③ Inductance is measured by current frequency of 1 kHz.

④ The value is based on ABI optical SIN/COS encoder (4096x interpolation) under maximum bus voltage.

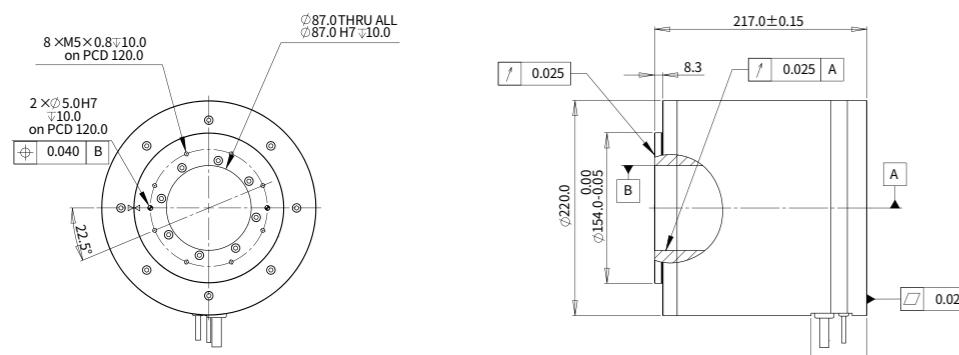
⑤ The runout value in parenthesis is optional.

⑥ Please refer to the illustration for different mountings.

⑦ Based on ABI optical SIN/COS encoder (4096x interpolation) with standard runout.

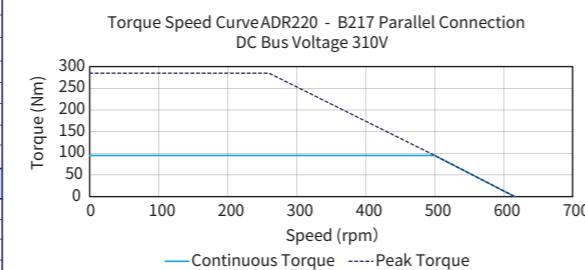
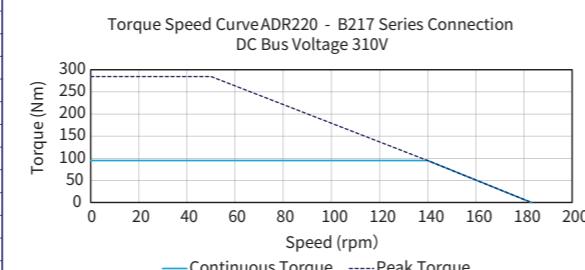
The contents of datasheet are subjected to change.

Dimension

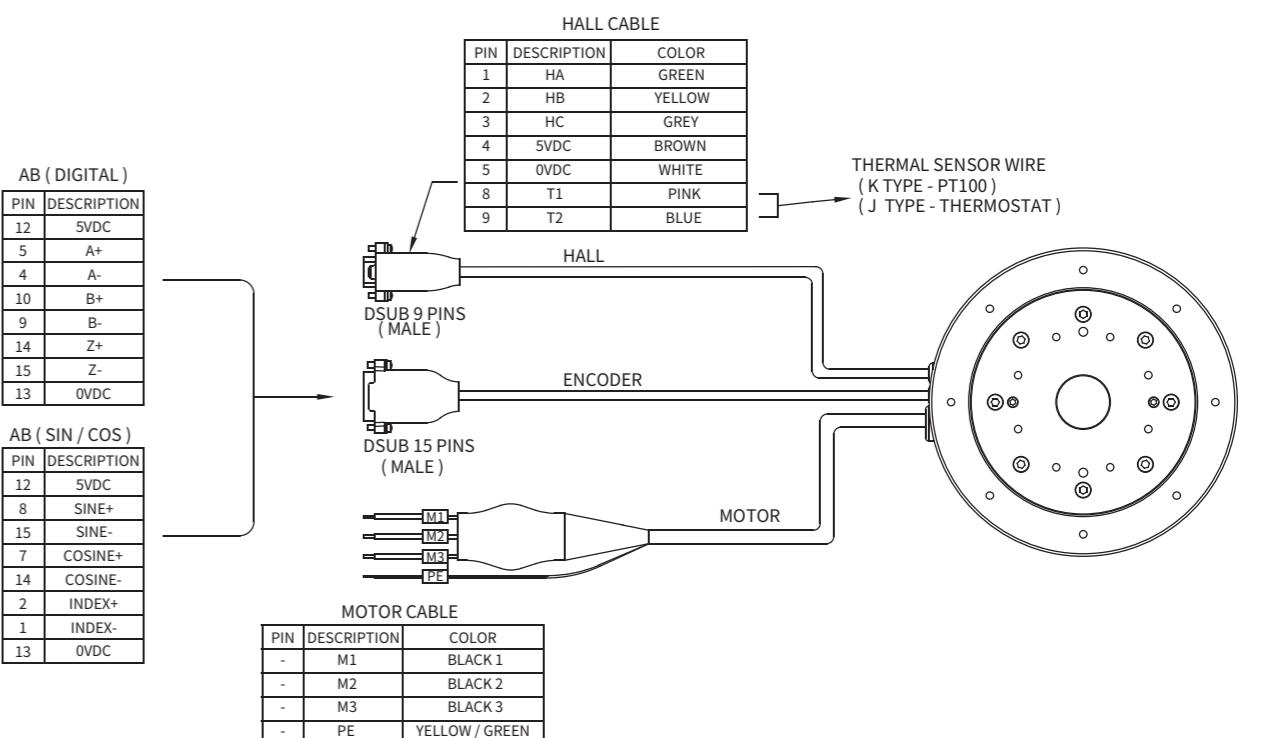


Standard cable length= 3.0m
 - Motor cable = Ø 0.95
 - Hall cable = Ø 0.52
 - Encoder cable = Ø 0.40
 (refer to Wiring Diagram for detail)

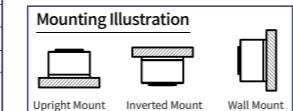
Torque-Speed Curve



Motor Cable Connection



Part Numbering



Motor: ADR110

Model: B113 / B136

Winding: S-Series / P=Parallel

Thermal Sensor: J=Thermostat(standard) / K=PT100(RTD)

Hall Cable Options: H9D / NH

① H9D = With Built-in hall sensor, comes with 9-Pins D-Sub Connector.
 ② NH = Without Built-in Hall Sensor but with Thermal Sensor.
 ③ FB = With ferrite bead.
 ④ P15 = Axial Runout 15um, Radial Runout is 15um.

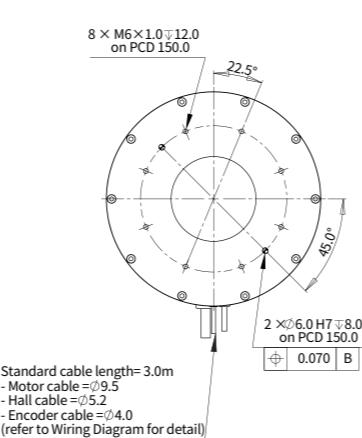
Runout: P15④

Interpolation Options: SINCOS 80X / 160X / 400X

Encoder Options: AB-3005

Motor Cable Options: FB③

Cable Length (m): 3.0



ADR135-B121-S-J-H9D-3.0-FB-AB-4103-SINCOS-P15

Motor:
ADR135Model:
B121 / B148Winding:
S-Series / P=ParallelThermal Sensor:
J=Thermostat(standard) / K=PT100(RTD)Hall Cable Options:
H9D / NHRunout:
P15Interpolation Options:
SINCOS
80X / 160X / 400XEncoder Options:
AB-4103Motor Cable Options:
FBCable Length (m):
3.0

- ① H9D = With Built-in hall sensor, comes with 9-Pins D-Sub Connector.
 ② NH = Without Built-in Hall Sensor but with Thermal Sensor.
 ③ FB = With ferrite bead.
 ④ P15 = Axial Runout 15um, Radial Runout is 15um.

ADR175-B180-P-J-NH-3.0-FB-AB-5071-SINCOS-P20

Motor:
ADR175 / ADR220Model:
ADR175-B143 / B180
ADR220-B167 / B217Winding:
S-Series / P=ParallelThermal Sensor:
J=Thermostat(standard) / K=PT100(RTD)Hall Cable Options:
H9D / NHRunout:
P20
P25Interpolation Options:
SINCOS
80X / 160X / 400XEncoder Options:
AB-5071Motor Cable Options:
FBCable Length (m):
3.0

- ① H9D = With Built-in hall sensor, comes with 9-Pins D-Sub Connector.
 ② NH = Without Built-in Hall Sensor but with Thermal Sensor.
 ③ FB = With ferrite bead.
 ④ ADR175 : P20 = Axial Runout 20um, Radial Runout is 20um.
 ADR220 : P25 = Axial Runout 25um, Radial Runout is 25um.